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CD

# Installation and operating instructions

## UFM 600 T ALTOSONIC





Variable area flowmeters

Vortex flowmeters

Flow controllers

Electromagnetic flowmeters

### **Ultrasonic flowmeters**

Mass flowmeters

Level measuring instruments

Communications engineering

Engineering systems & solutions

Switches, counters, displays and recorders

Heat metering

Pressure and temperature

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(I) current output (F) frequency output



# **ALTOSONIC** Introduction

UFM 600 T

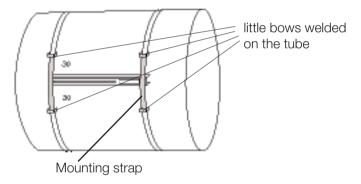
### **System Description**

The Altosonic UFM 600 T is an ultrasonic flowmeter which can easily be clamped on existing pipelines with inner diameters between 50 mm and 3000 mm (2" to 120") and pipe wall thicknesses up to 40 mm.

Measurement is performed obstructionless, without changing the existing pipework and without any headloss.

The UFM 600 T is an economical solution for all kinds of flow measurements of liquids containing no or little solid particles or gas.

Examples are: cooling water, waste water, oil, acids, bases etc.



At mounting on diameters > DN 1600, we recommend to weld 4 little bows on the tube as indicated in the sketch. See also Chap. C.1.1.



# ALTOSONIC System Description

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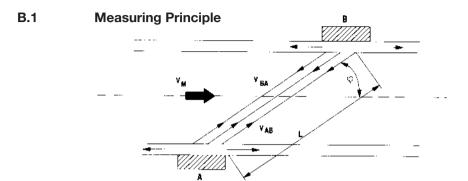


Fig. B.1: Measuring principle

A sound wave that is sent in the direction of the flow through a medium will travel faster than one that is sent in the opposite direction.

This principle is used in the ultrasonic transit time flowmeter. Two ultrasound transmitters/receivers are fitted on opposite sides of the pipe section as shown in Fig. B.1.

Initially transducer A transmits an ultrasonic sound signal that will be received by transducer B. The time lapse  $t_{AB}$  between transmission and reception is measured.

Then the functions of both probes are reversed and the transit time  $t_{\text{BA}}$  in the opposite direction is measured.

From  $t_{AB}$  and  $t_{BA}$  the actual flow can be calculated taking into account the following factors:

- pipe diameter
- wall thickness
- lining thickness, if applicable
- sonic velocity in the liquid
- sonic velocity in the pipe material
- sonic velocity in the pipe lining material, if applicable Measurements are taken continuously.

**NOTE**: Each transducer transmits and receives ultrasound signals.



# ALTOSONIC System Description

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### B.2 Measuring System

A microprocessor controls the transducers via an analog/digital interface and calculates the actual flow.

The control program is stored in EPROM memory.

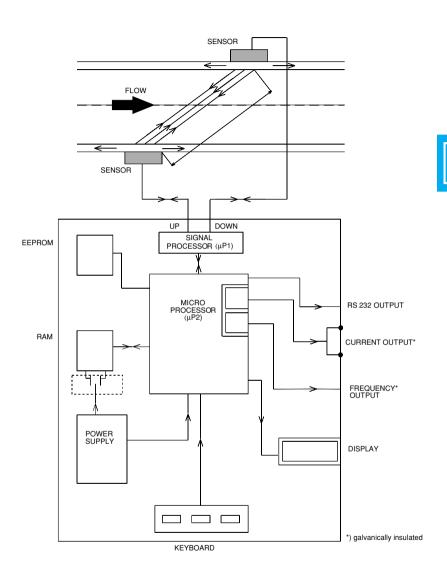
Parameters for the application and processing the data are entered via the keyboard.

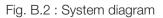
A liquid crystal display is used for the indication of all measuring data.

All data collected in the field can be stored in RAM memory and transferred to an IBM compatible PC via an RS 232 output; the same applies to the parameter settings.

Both current and frequency output signals are available for auxiliary readout and/or control purposes.

Figure B.2 shows a diagram of the flowsystem.







# **ALTOSONIC** System Description

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## B.3 Equipment

The UFM 600 T flowmeter is fitted in a sturdy case.

Figure B.3 shows the UFM 600 T with all items displayed:

3. Shielded cable (coax) 4. Grounding cable 5. Small mounting strap 6. Large mounting strap 7. Mounting rail 8. Acoustic coupling grease (22)	2x) 2x) 2x) 2x) 2x) 2x) 2x) 2x) (x)
- 3,5" diskette 10. Magnet bar (1	x)

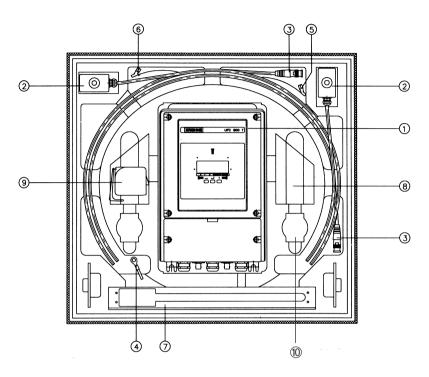




Fig. B.3: UFM 600 T with all equipment displayed

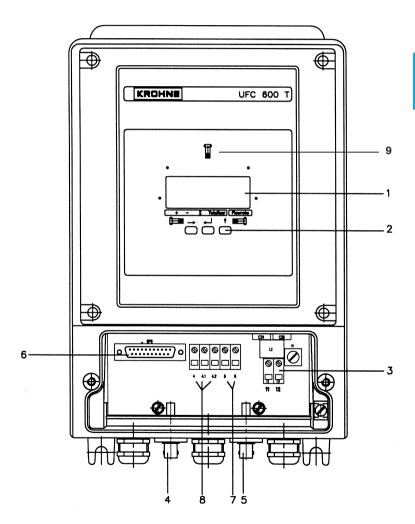
# **ALTOSONIC** System description

UFM 600 T

### B.4 Controls and Connections

Figure B.4 shows the controls and connections of the flowmeter unit.

- 1 Liquid crystal display
- 2 Keyboard (3 keys)
- 3 Power supply (term. 11,12)
- 4 Connector for upstream transducer
- 5 Connector for downstream transducer
- 6 RS 232 output for PC
- 7 mA-Output (term. 5, 6)
- 8 Frequency output (term. 4,.4.1, 4.2)
- 9 Hall contacts







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## **B.5** Transducers and Mountings (see Fig. B.5)

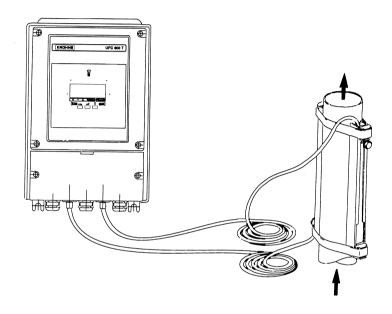


Fig. B.5 : Transducers, signal converter and auxillary items

Two mounting rails are clamped against the pipe wall by two straps.

The transducers can slide inside the mounting rails to obtain the correct distance between them. The transducers are then tightened firmly against the pipe wall.

Coupling grease is used between the transducers and the pipe wall to provide a good transfer of the ultrasound signal through the pipe material.

The transducers are connected to the control unit by means of two shielded cables.

## B.6 Display and Data Storage

### Display:

The following display options are available:

- Actual flow rate and direction.
- Total positive and negative flow volume since the start of the measuring session.
- Absolute flow volume since the start of the measuring session.
- Transit time of the acoustic signal.
- Error messages.
- Back lit function of the display.

Since the display shows only one read out at a time, they can be viewed sequentially.

### Collect data:

At a programmable interval, all flow information selected to be displayed can be stored and sent to a PC via the RS 232 output. Also the parameter settings can be send to a PC.



# **ALTOSONIC** System description

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### B.7 Direct Output

Both current and frequency output signals are available for control purposes. These can be either analog signals or just flow direction indicator signals.

To avoid adverse effects on equipment connected to the flowmeter a signal hold function can be activated; this is important if the flowmeter is being used as part of a control loop. When you terminate the measuring session the last output signal can be maintained.

### B.8 Power Supply

The flowmeter can be delivered in two versions for different power sources:

- AC Power supply 85 264 VAC
- DC power supply 18 32 VDC

When the unit is switched off, the data stored in the volatile memory is maintained by a backup battery on the microprocessor board.

This battery is capable of supporting the RAM for at least 5 years.



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## C.1 Initial Set-Up

The main steps of the installation procedure of the flowmeter are:

- 1 Install the mounting rails on the pipe.
- 2 Program the application parameters through the Start Up Menu, up to the point where the microprocessor calculates the transducer distance.
- 3 Install the transducers in the mounting rails, according to the microprocessor calculated distance.
- 4 If applicable perform a zero point calibration.

### C.1.1 Installation of mounting rails

Mounting Considerations:

The pipe section on which the transducers will be clamped must always be completely filled with liquid, even if there is no flow.

The transducers can be fitted on both horizontal and vertical pipe sections (or any other elevation).

On horizontal pipes the transducers should be fitted such that the ultrasonic pulse travels approximately horizontally through the pipe since gas/vapour at the top of the pipe or any contamination at the bottom can cause an obstruction to the ultrasonic pulses.

The solid or gas content of the liquid must not exceed 1 percent by volume.

Note that, due to cavitation, bubbles can appear behind valves, pumps etc., so the transducers should not be installed too closely to these positions.

The absolute minimum distances are given in the table below.

Highly distorted flow profiles may require significantly longer straight upstream lengths.

Upstream straight length	
- when mounted behind a pump	≥ 15 x DN
- when mounted behind a fully opened valve	≥ 10 x DN
- when mounted behind one or more elbows	≥ 10 x DN
- when mounted behind a reduction $\alpha/2,7^\circ$	≥ 5 x DN
Downstream straight length	≥ 5 x DN

(DN: Nominal Diameter)



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### Mounting Procedure:

- a Severe rust or thick coatings have to be removed from the pipe where the transducers will be installed.
- b Slide the securing straps through the slots on both ends of each mounting rail (see fig. C.1).

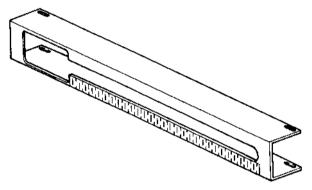


Fig. C.1: Mounting rail

c Attach the rails on opposite sides of the pipe such that the large slots point in opposite directions (see fig. C.2).

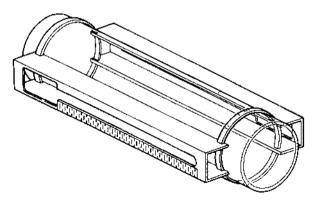
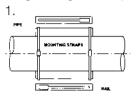
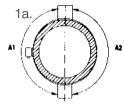


Fig. C.2: Mounting rails fitted on the pipe

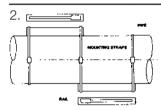
d Use the supplied tape measure to ensure that the rails are fitted diametrically opposite each other (see fig. C.3-1a.).

Distance A1 must equal distance A2. Secure the rails by tightening the straps.



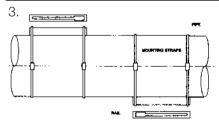


Mounting position if calculated transducer distance does not exceed 350 mm (14")





Mounting position if calculated transducer distance is between 350 mm (14") and 700 mm (28")



Mounting position if calculated transducer distance does exceed ≥ 700 mm (28")

Fig. C.3: Mounting positions

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### C.1.2 Programming the application parameters

After the flowmeter has been switched on it will start in the measuring mode.

Pressing twice the key enters the Start Up Menu. In this menu the application related parameters can be programmed.

All functions are described in section C.2.

#### **Push Button Functions**

The flowmeter can be programmed by means of the three keys located below the liquid crystal display.



By pushing the left-hand key 'ARROW RIGHT' the parameter shown on the display will be activated and the desired value can be entered or an option can be selected.



After pushing the key in the middle 'ENTER' the programmed information will be stored and the program advances to the next parameter.



For entering numbers or letters the 'ARROW UP' key must be used; this will increment the ASCII value of the blinking character (next higher number or next letter in the alphabet).

If a selection from a table must be made the 'ARROW UP' key can be used to display the next option in the table. After using the 'ARROW UP' key without actually programming a parameter the next parameter will be displayed.

## Input of values

Input of values outside the range, indicated at the function descriptions, will result in a flashing error message; the minimum or maximum value allowed is displayed above the error message.

After pressing any key the function is active again and the correct value can be entered.

### Start Up Menu

Enter all application parameters in the Start Up Menu; see section C.2 for full details. Continue until the transducer distance is on display. Now the transducers can be installed.



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### C.1.3 Installation of the transducers

Since the required transducer distance "S" is known now the transducers can be positioned in the rails:

- 1 Turn the transducer securing screw completely counter clockwise until the transducer positioning plate touches the top of the transducer housing.
- 2 Feed the coax cables through both mounting rails.
- 3 Cover the bottom of both transducers with a thick layer of the sonic coupling grease.
- 4 Connect each transducer to a coax cable and slide the transducers into the rails (fig. C.4.) While inserting the transducers, care must be taken not to touch the pipe wall with the transducers before the proper position is obtained, otherwise the coupling grease will be wiped off the transducers and the result will be a bad sonic coupling between the transducers and the pipe wall.

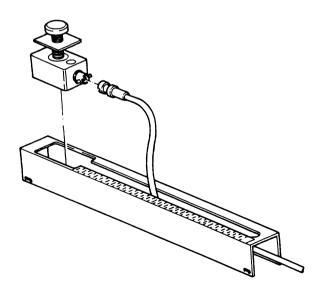


Fig. C.4: Position of transducer and cable

#### NOTE:

- The cable connections at the transducers must always point away from each other (fig. C.5).
- Make sure that the transducers are not placed over a welding seam.

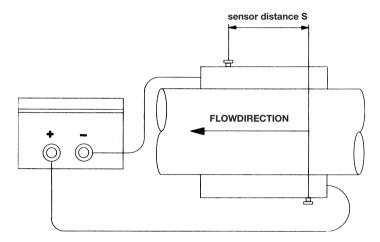




Fig. C.5: Upstream and downstream connection

- 5 Use the cm scale on the mounting rails to position the transducers at the proper distance from each other and hand tighten the securing screws.
- 6 Check using the indication of the low signal marker (see C 3.1) whether the unit is functioning properly.

Continue with Zero Set function (C.1.4.)

## NOTE: REMOVAL OF THE TRANSDUCERS FROM PIPE WALL

When removing the transducers from the pipe wall, especially after they have been in place for a long period, care should be taken:

- Not to damage the tranducers by pulling strongly at the securing screw.
- Therefore, to remove a tranducer, it must be removed in a slicing motion. Do not just pull it straight off the pipe all !!

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### C.1.4 Zero set / Zero point calibration

#### Zero Set

After leaving the transducer distance function the ZERO SET function can be activated.

The flowmeter is functioning now without displaying any flow readings. Only the low signal marker (see C.3.1) gives an indication of the signal quality based on the factory set default zero point calibration.

The low signal marker will indicate if a zero point calibration is feasible.

A zero point calibration is strongly advised as this will improve the overall accuracy.

If no zero point calibration is to be executed, this function can be skipped.

See also section C.3, Error Detection, for the accuracy to be expected.

### **Zero Point Calibration**

Before performing the zero point calibration ensure that:

- The unit is functioning properly (see low signal marker).
- There is no flow at the location where the transducers are installed and the pipe section is completely filled with liquid.

Now activate the Start Up Menu and enter the ZERO SET function:

- With → DEFAULT or MEASURED will be visible
- Use to select between DEFAULT or MEASURED
- If DEFAULT is selected press to set the preprogrammed DEFAULT zero point
- If MEASURED is selected press 

  ✓
- Now CALIB. NO will be visible.
- Use 

  ↑ to select YES and press 

  ◆
- The microprocessor now performs an input signal test.
- On the top line the zero point correction in % is displayed.
- If the correction is near 0% the calibration was successful; select STORE YES and press to save the zero point calibration.

If no reliable signal is detected the error message BAD ZERO is displayed and the calibration should be abandoned; in order to restart the zero point calibration procedure. The data collection can be started now or other parameters can be entered through the programming mode (chapter D).

### NOTE:

MEASURED zero point is selected if there is no flow. DEFAULT zero point should be selected if the flow cannot been stopped.



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### C.2 Start Up Menu

### C.2.1 Enter start up menu

The Start Up Menu is activated by pressing the → key twice from the measuring mode or pressing the → key once from the main menu 1.0.0.

### C.2.2 Application Functions

The functions in which the application parameters can be programmed always appear on the display in the same order as described below:

To enter a next function, the [+] key must be pressed.

#### DIAMETER

Program the outer pipe diameter.

The diameter can be entered either in mm or in inches.

### Range:

```
2.0000 E 0 mm ≤ DIAMETER ≤ 4.0000 E 3 mm
7.8740 F-2 inch < DIAMETER < 1.5748 F 2 inch
```

#### PIPEWALL

Program the pipe wall thickness.

The wall thickness can be entered either in mm or in inches.

### Range:

```
1.0000 E-1 mm ≤ PIPEWALL ≤ 5.0000 E 1 mm
3.9370 E-3 inch ≤ PIPEWALL ≤ 1.9685 E 0 inch
```

#### PIPE MAT.

Program the sonic velocity of the pipe material.

The following 5 options are preprogrammed (or will reappear after running 3.5.8 DEFAULT SET, see chapter D):

 STEEL
 :
 3.1700 E 3 m/s

 ST. STEEL
 :
 3.1200 E 3 m/s

 IRON
 :
 2.1200 E 3 m/s

 PVC
 :
 2.1200 E 3 m/s

 Other
 :
 1.5000 E 3 m/s

All five option positions can be reprogrammed completely according to the user's requirements (names and sonic velocities).

The sonic velocity can only be programmed in m/s.

### Range:

1.5000 E 3 m/s  $\leq$  Sonic velocity  $\leq$  4.7500 E 3 m/s See appendix 1 for sonic velocities of the most frequently used pipe materials.

#### TITNTNG

Select YES or NO depending on whether or not the pipe is provided with a lining.

When NO is selected the parameters LINING THICKNESS and LINING MATERIAL can not be programmed.

#### LINING TH.

(does not appear on display when lining = "NO")

The lining thickness can be entered either in mm or in inches.

### Range:

1.0000 E-1 mm  $\leq$  LINING THICKNESS  $\leq$  5.0000 E 1 mm 3.9370 E-3 inch  $\leq$  LINING THICKNESS  $\leq$  1.9685 E 0 inch



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LINING MAT.

(does not appear on display when lining = "NO")

Program the sonic velocity of the lining material.

The following 5 options are preprogrammed (or will reappear after running 3.5.8 DEFAULT SET, see chapter D):

PVC : 2.1200 E 3 m/s
Other 1 : 1.0000 E 3 m/s
Other 2 : 1.0000 E 3 m/s
Other 3 : 1.0000 E 3 m/s
Other 4 : 1.0000 E 3 m/s

The sonic velocity can only be programmed in m/s.

### Range:

 $3.0000 \to 2 \text{ m/s} \le \text{Sonic velocity} \le 4.7500 \to 3 \text{ m/s}$  See appendix 1 for sonic velocities of some lining materials used frequently.

All five option positions can be reprogrammed completely according to the user's requirements (names and sonic velocities).

#### LIOUID

Program the sonic velocity of the liquid inside the pipe. The following 5 options are preprogrammed (or will reappear after running 3.5.8 DEFAULT SET, see chapter D):

WATER : 1.5000 E 3 m/s
Other 1 : 1.0000 E 3 m/s
Other 2 : 1.0000 E 3 m/s
Other 3 : 1.0000 E 3 m/s
Other 4 : 1.0000 E 3 m/s

The sonic velocity can only be programmed in m/s.

### Range:

1.0000 E 2 m/s ≤ Sonic velocity ≤ 2.5000 E 3 m/s See appendix 2 for sonic velocities of frequently encountered

See appendix 2 for sonic velocities of frequently encou liquids.

All five option positions can be reprogrammed completely

according to the user's requirements (names and sonic velocities).

#### NOTE:

If the sonic velocity is not known it can be estimated by using the sonic velocity calculation, see appendix 3.

### FULL SCALE

Select the flow rate units and program the full scale value. A selection can be made out of 9 preprogrammed units and one unit can be specified by the user (see function 3.5.3, 3.5.4 and 3.5.5 in chapter D).

Unit	Range	
m3/Sec m3/min m3/hr Liter/Sec Liter/min Liter/hr US G/Sec US G/min US G/hr	9.4240 E-7 5.6533 E-7 3.3926 E-3 9.4240 E-4 5.6544 E-2 3.3926 E 0 2.4896 E-4 1.4937 E-2 8.9624 E-1 9.4240 E-7	≤ F.S. ≤ 1.5080 E 2 ≤ F.S. ≤ 9.0481 E 3 ≤ F.S. ≤ 5.4288 E 5 ≤ F.S. ≤ 1.5080 E 5 ≤ F.S. ≤ 9.0481 E 6 ≤ F.S. ≤ 5.4288 E 8 ≤ F.S. ≤ 3.9837 E 4 ≤ F.S. ≤ 2.3902 E 6 ≤ F.S. ≤ 1.4341 E 8 ≤ F.S. ≤ 1.5080 E 2 (user defined unit)



### LOCATION

The name of a measuring site or tag number can be programmed here. When function 3.6.5 is activated (see chapter D) the location name will be recorded in the header of each data block that is stored.

SENS. DIST.

After the previous parameters in the Start Up Menu have been programmed, the microprocessor will calculate, either in mm or inches as chosen for under diameter, the desired distance between the two transducers, measured along the pipe axis. Enter this function to read the result on the display.

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ZERO SET:

Zero point calibration.

Select between the factory set default value for the zero point or perform a zero point calibration for the actual situation.

See paragraph C.1.4 for the precise conditions and instructions for a calibration.

### C.2.3 Plausibility check

After any changes are made to the parameter settings the microprocessor will perform a plausibility check on the changed settings, before the measuring mode can be activated. If no "impossibilities" in the configuration are detected the microprocessor asks for confirmation before the new settings are stored.

If discrepancies in the parameters entered are found the microprocessor will display the message "PARAMERROR" which prevents you from storing parameters that are incorrect; the options available to correct the configuration are described in section D.6.

The next function which will appear is again, the first function of this Start Up Menu: "DIAMETER".

The Start Up Menu is left by pressing the wey once from any function name in the Start Up Menu. When doing this, the Main Menu will be entered (function 1.0.0.)

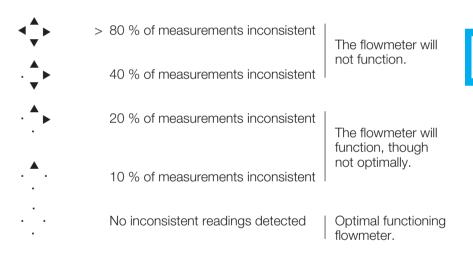
### C.3 Error Detection

## C.3.1 Low signal marker function

The condition of the input signal from the transducers is indicated by a marker in the top left hand corner of the display. The marker consists of four arrows divided over 360 degrees.

The microprocessor calculates the percentage of the measurements that is inconsistent.

### Marker indications:



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### C.3.2 Error messages

If the microprocessor produces an error message a \* sign appears at the lower left hand side of the display.

Enter the QUIT / RESET mode to view the error message(s) (see chapter C.5).

It depends on the settings of the Installation functions 3.2.4 and 3.2.6, whether the error messages will be displayed in between the flow data.

### List of Error Messages:

SIGN LOST : Transducer disconnected

TOTALIZER: Overflow of the totalizer.

FREQ.OUTP. F: Overflow of the frequency signal; full

scale value is too small

CUR. OUTP. I: Overflow of the current signal; full

scale value is too small

CAL. DATA: The transducer calibration is

distorted: contact vour supplier

EE1 EE2 : Error detected during memory check;

switch unit off and on; if message still reappears after two attempts, contact

your supplier

EEPROM2 : See EE1 EE2

ROM : Checksum error detected during

memory test; contact your supplier

RAM : Error detected during verification of

parameter settings stored previously; use function 3.5.8 DEFAULT SET and

switch off and on; if message reappears contact your supplier.

STORE: A total number of 350 data blocks are

been stored. Rest capacity 40 data

blocks till data storage is full.

FATAL ERROR: Check sum error detected; contact

your supplier.

PARAMERROR: This message will not appear during

measurement; at the end of both the start up menu and the programming mode a parameter check is performed before the measuring mode can be entered (see section D.6).



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#### C.4 Data Collection

### C.4.1 Data collection procedure

### Sampling Rate / Data Storage Capacity

A total number of 390 data blocks can be stored.

This number is independent of the amount of information that is programmed to be on display and/or stored.

It is very important to determine a useful combination of the measuring period and the data sampling rate.

If the flow rate shows only minor fluctuations or fluctuations are not relevant a low sampling rate can be programmed. Thus a long measuring period can be achieved or more than one data collecting interval can be realized before the data has to be transferred to a PC.

If the flow rate fluctuations are important the sampling rate should not be too low. Otherwise, relevant information might not be recorded.

#### NOTE:

When all 390 data blocks are occupied no further data will be stored. The flowmeter will continue to operate normally. WARNING IS GIVEN WHEN THE DATA STORAGE IS FILLED WITH 350 DATA BLOCKS (See chapter C.3.2. Error Messages)

#### Reset Data

If a new measurement series is started (previous flow data can be discarded) the data blocks can be cleared; two RESET DATA functions are available:

- 1 use the function 3.6.6, RESET DATA, in the programming mode
- 2 enter the QUIT/RESET menu (see section C.5.) from the measuring mode and select the RESET DATA option.

#### Reset Totalizers

If applicable the totalizers must be reset at the beginning of a measuring series. Enter the QUIT/RESET menu from the measuring mode and select the totalizer(s) that have to be reset (see section C.5)

#### **Preparation for new measurements**

Providing any previous flow data can be discarded, a data collection session can be started as follows:

- 1 Select the STORE or BOTH option of function 3.6.3 in the programming mode
- 2 Clear the RAM by means of one of the two ways to Reset Data
- 3 Start the measuring mode
- 4 If applicable reset the totalizers

#### **Preparations for continued measurements**

It is advisable not to activate the STORE option of function 3.6.3 in the programming mode until the actual measuring period is to be started; otherwise unnecessary data blocks are being stored and storage space is lost.

After installing the transducers it is advisable to run in the measuring mode for some time during which the data is only sent to the display (function 3.6.3 OFF).

The readings can be checked and adjustments made (e.g. adjust full scale value) to ensure that the suitable data is collected.

The actual measuring period with data storage (and the RAM partially filled) can then be started as follows:

- 1 Select the STORE or BOTH option of function 3.6.3 in the programming mode
- 2 Leave the programming mode and enter the measuring mode via the DIAMETER prompt of the Start Up menu
- 3 If applicable, reset the totalizers



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### C.4.2 Transfer to PC (data and parameters)

#### Software

The floppy disk provided contains programs for the transfer and conversion of the measuring data:

- GETFLOW.EXE

Function : Transfer measuring data and/or

parameter settings to the PC

The information will be stored in ASCII

format.

Syntax : GETFLOW <com> <file>

<com> : the number of the serial

port on the PC.

<file> : file name for the data to

be stored.

- FLOW2CFL.FXF

Function : Convert the ASCII data for processing

by Harvard Graphics, VP Planner or

Lotus 1.2.3.

Syntax : FLOW2CEL <input file> <output file>

<Language>
WITH Language:
E = English
D = Deutsch
F = Francais
N = Nederlands

**NOTE:** Both programs show their syntax if they are run without or with false extensions.

- README E.DOC

If applicable this file offers an update on the software infor-

mation.

#### Data transfer

For the transfer of information from the flowmeter to the PC proceed as follows:

- Connect the RS 232 cable to the flowmeter and the serial in/output port of the PC (com1 or com2).
- Enter the programming mode of the flowmeter and activate the function 3.6.1 or 3.6.2 for either the output of the parameter settings or the measuring data; see that the selection is on YES
- Run program GETFLOW on the PC
   For example if the Com1 port is connected and the data has to be stored in file FLOW.DAT then type:
   GETFLOW 1 FLOW.DAT
  - The message WAITING FOR DATA will appear.
- Now press [4] on the flowmeter within 3 seconds.
- The data is transmitted to the PC and stored in the file indicated using the ASCII format.

# R

#### **Data conversion**

After all flow information is stored in an ASCII file use program FLOW2CEL to convert the data to a format that can be adapted for presentation purposes.

Run program FLOW2CEL on the PC and follow the instructions displayed.

See README E.DOC for any additional information.

# C.4.3 Terminal programs

Standard terminal programs (e.g. MS Windows® terminal) can be used to receive data from the UFC 600 T signal converter by using a straight RS 232 cable with 25 pins female D-connector.

Settings must be: BAUDRATE 2400

DATA BITS 7
STOP BITS 1
PARITY NONE

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### C.5 Quit / Reset Menu

The measuring mode can be exited with the code as described below to enter the Quit/Reset Menu. In this menu two functions can be used:

#### ERRORLIST:

Show the list of errors indicated by the  $^{\ast}$  sign at the left-hand side of the display.

When the error messages are not programmed to appear on a regular display (function 3.2.4 and 3.6.4) the only way to recognize an error (apart from the low signal marker) is by the \* sign at the left-hand side of the display.

Enter the error list with the  $\longrightarrow$  key; the number of errors and the first error message will be visible. Use the  $\bigcirc$  key to display the other error(s); eventually the ERR.ACQUIT function will appear.

### ERR.ACQUIT function:

After curing the cause of the error(s) enter the ERR.ACQUIT function by using the  $\rightarrow$  key and select YES with  $\uparrow$  key to reset the error message and error marker \*.

Even if the cause of an error is cured the error message and the error marker will not disappear until they are cleared by the ERR.ACQUIT function.

\* Note that these error messages differ from those included in the data block that is stored and sent to the RS 232 output at regular intervals (function 3.2.4 and 3.6.4): at the end of the next complete data collection interval following the elimination of the errors these messages will have disappeared automatically.

#### RESET:

In this submenu three reset options are available:

TOTAL + : Reset + totalizer.

TOTAL - : Reset - totalizer.

RESET DATA : Reset all data blocks.

In each option YES or NO must be selected.

The reset option is to be used to obtain a clear start of a data sampling session.

#### CODE:

The code to exit the measuring mode and to enter the Quit/Reset mode is:  $\blacksquare$ 



Although the code is rather simple it prevents the collected data from being wiped out unintentionally.

If within 3 or 4 seconds the proper code has not been entered the measuring mode is resumed without having been interrupted.

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# C.6 Direct Output Ports (Analog (mA) output and frequency / pulse output)

#### C.6.1 General

The options available for these direct output ports are described further in section D.4 main menu: 3.0.0 INSTALLATION.

Refer to the technical specifications if any equipment is to be connected to the current and/or frequency output. (see C.6.3, C.6.4 and chapter F)

### C.6.2 Output hold

It is advisable to activate the output hold function (3.5.2) when the flowmeter is being used as part of a control loop.

**NOTE:** This hold function also affects the outputs in case of malfunction (signal lost).

### C.6.3 Current output

Specification:

Range: 0 to 20 mA, or 4 to 20 mA or I

0% to...;I 100% programmable

Load :  $R_{L}[kohms] < \frac{14 [M]}{1100\% [mA]}$ 

(e.g. 0.7 kohms at 20 mA, 2.8 kohms at 5 mA).

## C.6.4 Frequency output

Specification:

Pulse rate for Q=100%: 10 to 36 000 000 pulses per hour

0.167 to 600 000 pulses per

minute

0.0028 to 10 000 pulses per

second (=Hz)

optionally in pulses per liter, m<sup>3</sup> or

US gallons

Active output short-circuit-proof

Terminals 4.1/4.2 : for electromechanical (EMC) or

electronic (EC) totalizers

Terminals 4/4.1/4.2: for electronic (EC) totalizers

Amplitude : approx. 27 V

Load rating see Table "pulse width"

Passive output

Terminals 4/4.1 : open collector for connection of

active electronic totalizers (EC)

or switchgear

Input voltage : 5 to 30 V Load current : max. 100 mA

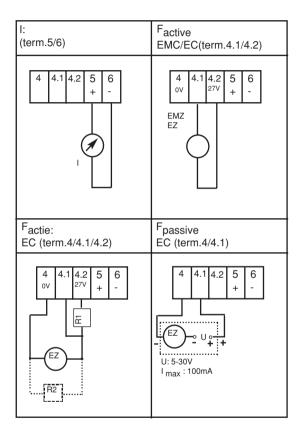
# Pulse width is automatically choosen, depending on actual out frequency.

Frequency f at Q=100%	Pulse width	Load rating of active output Load current Load		
0.0028 Hz < f ≤ 1 Hz	500 ms	≤ 150 mA	≥ 180 Ohm	
1 Hz < f≤ 10 Hz	approx. 50% duty cycle (1:1)	≤ 25 mA	≥ 1 k Ohm	
10 Hz < f≤ 1000 Hz	50% duty cycle (1:1)	≤ 25 mA	≥ 1 k Ohm	
1000 Hz < f≤ 2547 Hz	160 µs	≤ 25 mA	≥ 1 k Ohm	
2547 Hz < f≤10000 Hz	50 µs	≤ 25 mA	≥ 1 k Ohm	



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## C.6.5 Connection Diagrams





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## C.7 Trouble Shooting

- The flowmeter does not respond after connection to the main power supply (no display or output messages).
  - Check fuse.

### 2 The error marker \* appears on the display

- Leave the measuring mode and enter the Quit/Reset menu

(press ; see section C.5). Cure the cause if necessary, and select ERR.ACQUIT to reset the error marker.

### 3 Low signal marker: 3 or 4 markers on.

Cause	Solution
Incorrect transducer	Reposition transducers (see section position C.1.3) using sufficient coupling grease and check the transducer distance afterwards.
Poor sonic coupling between pipewall and transducer surface	Check the pipe wall surface; remove any rust, dirt and/or thick layers of paint or coating. Apply sufficient grease on the transducers and make sure not to wipe off any grease from the transducers while they are being reinstalled.
Pipe is not completely filled	Fill the pipe completely or select a pipe section that is always completely filled with liquid.
Broken signal cable	Use a multimeter to check the condition of the cables and the connectors. See your supplier for

replacements. If 3 or 4 markers remain the selection of a different location on the pipe wall is recommended; some irregularities at the interior of the pipe might have caused poor signal reception.

#### 5 Low signal marker: 1 or 2 markers on.

#### Cause

#### Solution

Small deviation of the the correct value

Adjust one transducer approx. transducer distance from ± 5 mm. until the markers disappear; do this very carefully so as not to disturb the sonic coupling grease layer between the transducer and the pipe wall.



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### D.1 General

In the main menu, two Sub Menus can be activated:

Sub Menu 2 "TEST":

Four function tests can be executed:

- Display test
- Microprocessor test
- Current output test
- Frequency output test

Sub Menu 3" INSTALLATION":

Enter all parameters that determine the initial settings of the flowmeter and the way the data is processed.

All functions available in both of these menus are listed in section D.3 and described further in sections D.4 and D.5.

### D.2 How to Program

Push button functions:



move the menu pointer one step to the right to activate the submenu displayed.



either move the menu pointer to the left to leave a submenu or store entered data and leave the submenu



will increment the ASCII value of the blinking character by one; either the next higher number or the next letter in the alphabet. Pushing this button in the measuring mode, the display will be illuminated for one hour.

Entering the Start Up Menu:

The Start Up Menu is entered by pressing twice the → key from the measuring mode or from the main menu 1.0.0. by pressing the → key once. The Start Up Menu is left by pressing the → key (once to return to main menu 1.0.0, four to return to measuring mode)



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#### Menu selection:

By entering the main menu, the submenu Start Up 1.0.0. will be on display; use the 1 key to select the submenus TEST 2.0.0. or INSTALL 3.0.0.

If the Start Up Menu is to be selected, press → key when 1.0.0. is displayed.

#### **Function selection:**

Use the  $\fbox{$\star$}$  key to select a function from the chosen submenu.

Activate the selected function by pressing the → key.

### Enter numbers, characters and select units:

If applicable within a function, numbers, characters or units can be selected at the position which shows a blinking sign by using the 1 key.

This position is selected by using the  $\rightarrow$  key.

The set up of the function is completed by pressing ; the data is stored and the menu pointer returns to the active submenu

#### Leave Submenu:

Press 🕡 to return to the main menu.

# **Ending the programming session:**

Ending a programming session can be done by pressing 4 3 times while one of the submenus (1.0.0, 2.0.0 or 3.0.0.) is active.

The programmed parameters will be saved directly without a request whether the changes should be set.

After saving the parameters the microprocessor will go directly to the measuring mode.

If any discrepancies are detected the error message PARAMERROR is displayed and a separate menu is activated in which the parameters concerned can be corrected (see section D.6).

#### NOTE:

To save the programmed parameters in the Start Up menu (fct. 1.0.0) press three times.

The signal converter is equipped with magnetic sensors (hall contacts). This allows setting of the signal converter by means of a hand-held bar magnet. Function of sensors without removing the front cover is the same as the corresponding keys.

Hold the bar magnet by the black rubber cap. Apply blue end of the magnet (north pole) to the glass pane above the magnetic sensors.



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D.3	List of Functions	
2.00	TEST	
<b>2.1.0</b> 2.1.1	<b>DISPLAY</b> DISP.TEST	
<b>2.2.0</b> 2.2.1	PROCESSOR 8048 TEST	
<b>2.3.0</b> 2.3.1	CURR. OUTP. TEST I	
<b>2.4.0</b> 2.4.1	FREQ. OUTP. TEST F	
3.0.0	INSTALLATION	
<b>3.1.0</b> 3.1.1 3.1.2 3.1.3 3.1.4 3.1.5	FLOW DATA (Submenu) PRIM. CORR.(Function) TRAN. RANGE LF. CUTOFF CUTOFF ON CUTOFF OFF	Set flow parameters.
<b>3.2.0</b> 3.2.1 3.2.2 3.2.3 3.2.4 3.2.5 3.2.6	DISPLAY DISP.FLOW DISP.TOTAL UNIT TOTAL ERROR MSG. DISP TRAN. T. CYCL. DISP.	Set output functions, L.C.Display and define the contents of the data blocks.
<b>3.3.0</b> 3.3.1 3.3.2 3.3.3 3.3.4 3.3.5	CURR. OUTP. FUNCTION I I 0 PCT. I 100 PCT. I MAX. T- CONST I	Set up analog output.

<b>3.4.0</b> 3.4.1 3.4.2 3.4.3 3.4.4	FREQ OUTP. FUNCTION F PULSOUTP. PULSRATE PULS/UNIT T- CONST. F	Set up frequency/pulse output.
3.5.0 3.5.1 3.5.2 3.5.3 3.5.4 3.5.5 3.5.6 3.5.7 3.5.8 3.5.9	SPEC. FCT. LANGUAGE OUTP. HOLD UNIT TEXT FACT. QUANT. FACT. TIME SET DATE SET TIME DEF.SET SOFTW.V - NR.	Set special functions.
<b>3.6.0</b> 3.6.1 3.6.2 3.6.3 3.6.4 3.6.5 3.6.6	COMM.DATA OUTP. PARAM OUTP. DATA SEL. COMM. INTERVAL LOCAT. RESET DATA	Set Store/RS 232 output.



**NOTE:** The function names used in the description of the functions are presented in the same way as on the L.C. display.

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#### **D.4** Sub Menu: 3.0.0 INSTALLATION

3.1.0 FLOW DATA : set flow parameters

3.1.1 PRIM. CORR. : Primary Correction

This function allows the user to correct the primary constant that is calculated by the microprocessor. Corrections on the primary constant are useful in the case of for example poor installation conditions or comparison to a reference flowmeter.

The primary constant will be multiplied by the number displayed; 1.0000 E0 means no correction and 1.1000 E0 indicates a correction of + 10%.

Range: 0.0000 E0 ≤ Prim. Corr.≤ 2.0000 E0

3.1.2 TRAN. RANGE: Transit (time) Range

Use this function only if the transit time of the acoustic signal (the time elapsed between transmission and reception) is used as output on either the current or the frequency output (see Fct. 3.3.1 and 3.4.1).

The transit time value that corresponds to 100% output is programmed.

Range: 2.0000 E1 ≤ Tran. Range ≤ 1.0000 E5 µsec

### Current output example:

If 200 µsec is entered and the 0 - 20 mA output is being used then an actual transit time of 150 µsec provides a 15 mA output signal. Likewise, if a 4 - 20 mA output is being used, a 16 mA signal would be the analog output.

# Frequency output example:

If 200 µsec is entered and the pulse rate at full flow is programmed to be 10000 Hz then an actual transit time of 120 µsec is indicated by a 6000 Hz signal.

#### 3.1.3 L.F. CUTOFF : Low Flow Cutoff

To avoid erroneous measurements at low flow rates the Low Flow Cutoff can be used (see Fig. D.2).

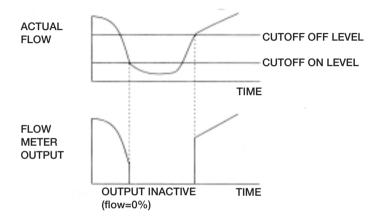


Fig. D.2: Low flow cutoff

If the flow rate drops below the "Cutoff On" level all outputs will be switched off and if the flow rate exceeds the "Cutoff Off" level the outputs will be activated again.

The "Cutoff On" level must be lower than the "Cutoff Off" level otherwise a PARAMERROR message appears at the parameter check (see section D.6).

After entering the function either YES or NO can be selected. If YES is selected functions 3.1.4 and 3.1.5 become active. If NO is chosen the low flow cutoff becomes inactive and functions 3.1.4 and 3.1.5 will not appear on the display.



# $\boldsymbol{ALTOSONIC}_{\text{Programming mode}}$

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3.1.4 CUTOFF ON : (only if at 3.1.3 YES was

entered)

Program the flow rate level below which all outputs will be switched off.

Enter the value in % of the full scale.

Range: 1 - 20

**NOTE:** This value must be lower than the Cutoff Off value!!

3.1.5 CUTOFF OFF : (only if at 3.1.3 YES was

entered)

Program the flow rate level at which all outputs become active again.

Enter value in % of full scale.

Range: 1-20

3.2.0 DISPLAY : set output functions L.C.display

L.O.dispia

**NOTE:** All functions that are programmed to be on display can also be saved as programmed in function 3.6.3 SEL.COMM.

3.2.1 DISP. FLOW: Display Flow rate

Determine whether the flow rate should be displayed and if so, in what sort of units; select a display option using the

key and press to store:

NO DISPLAY:
m3/Sec:
m3/min:
m3/hr:
Liter/Sec:
Liter/min:

Liter/hr :

US G/Sec : U.S. Gallon per second

US G/min :

US G/hr :

in Start Up menu

3.2.2 DISP. TOTAL : Display Totalisator

outputs

Select which totalizer outputs should be displayed by using the 1 key and press 1 to store:

NO DISPLAY: (function 3.2.3 will not appear)
+ TOTAL: Totalizer for positive flow
- TOTAL: Totalizer for negative flow
+/- TOTAL: Totalizers for both positive and

negative flow

SUM TOTAL: [+ TOTAL]- [- TOTAL]

ALL TOTAL : All three totalizer options are active



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3.2.3 UNIT TOTAL

(only if a totalizer has	s been set in 3.2.2)
Select unit for the to	otalizers using the 🚹 key and press
m3 Liter	:
US G	:

3.2.4 ERROR MSG. : Display Error Messages

Determine whether error messages should be displayed and if so, what type of error messages; select a message option using the 1 key and press 4 to store:

NO MESSAGE :

US ERROR : Only display of errors

related to the measure-

ment itself

unit for totalizers

User defined unit

TOT. ERROR : Display of totalizer

errors only

ALL ERROR :

3.2.5 DISP. TRAN. T: Display Transit Time

The transit time is the time lapse between transmission of the acoustic signal by one transducer and the reception of the signal by the opposite transducer.

Select display of the transit time; choose either YES or NO using the 1 key and press 1 to store.

3.2.6 CYCL. DISPL. : Cyclic Display

The cyclic display option can be used to automatically change the function of the display, if more than one variable is programmed to be displayed.

Only one variable can be shown on the display at a time. With this option active the display sequences from one variable to the next every 5 seconds.

If the error messages are programmed to be displayed, these appear in between the successive variables, if applicable. For the totalizers and the flow rate, the actual function of the display is indicated by an arrow symbol  $\blacktriangledown$  at the bottom of the display.

If NO is selected the successive display of the variables is obtained by using the | | key.



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3.3.0 CURR. OUTP.I : set up analog current

output

3.3.1 FUNCTION I : Program the analog

current output

Select an output option using the 🚹 key and press 🗗

to store:

2 DIR : Enables flow measurement in 2 direc-

tions(+ and -) without change polarity in the output signal (Fig. D.3)

TRAN. TIME : Output signal is proportional to

the measured transit time of the

acoustic signal.

NOTE: this function requires:

- current setting at zero flow, Fct. 3.3.2

- current setting at full flow, Fct. 3.3.3

- transit time at full flow, Fct. 3.1.2 (see example in description of Fct. 3.1.2)

NO SIGNAL : Output signal indicates "signal loss".

OFF: No current output.

F/R IND. I : Output signal as flow direction

indication, 0% at + flow direction and 100% at -flow direction

(fig. D.4).

1 DIR : Flow measurement in 1 direction

(+) only. (Fig. D.5)

I < I 0 PCT : Allows the output signal to drop

below the programmed value for

0% flow at negative (-) flow

direction. If 10 mA is programmed for 0% flow (Fct.3.3.2) and 20 mA for 100% (Fct. 3.3.3) then the output will

### be 0 mA at - 100% flow (fig. D.6)

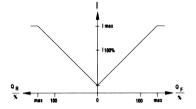


Fig. D.3: Bi-directional flow (I)

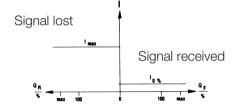


Fig. D.4 : Flow direction indication (I) or signal loss indication (I)



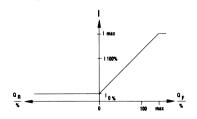


Fig.D.5: Positive flow (I)

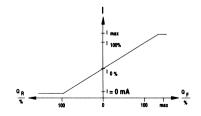


Fig. D.6: Negative flow and output (I)

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3.3.2 [I 0 PCT] : Program current output

at 0 %flow

Range:  $00 \text{ mA} \leq [10 \text{ PCT}] \leq 16 \text{ mA}$ 

NOTE:

This value must be lower than the [I 100 PCT] value!! If this is not the case, a PARAMERROR message will appear during the parameter check procedure.

3.3.3 [I 100 PCT] : Program current output

at100% flow.

Range:  $04 \text{ mA} \leq [1 100 \text{ PCT}] \leq 20 \text{ mA}$ 

[I 100 PCT] must exceed [I 0 PCT] by at least 4 mA; if this is not the case, a PARAMERROR message appears during the parameter check (see section D.4).

3.3.4 [I MAX] : Program maximum out

put current

The maximum output level can be limited to protect accessory equipment.

Range:  $04 \text{ mA} \leq 1 \text{ MAX} \leq 22 \text{ mA}$ 

[I MAX] must be equal to or greater than [I 100 PCT]; if this is not the case, a PARAMERROR message appears during the parameter check (see section D.4).

3.3.5 T - CONST.I : Time constant of current output

rent output

To flatten out sudden fluctuations in the current output signal a first order filter is included.

Program the time constant for the current output: Range:  $4.0000 \text{ E-2} \le \text{T} - \text{CONST.} \le 3.6000 \text{ E} 3$ 

Recommended initial value : 2 to 5 sec.

ATTENTION: Time constant also affects readings on LC-display.

3.4.0 FREQ. OUTP. F: set up frequency / pulse output

3.4.1 FUNCTION F : Program the analog fre-

quency output

Select an output option using the [+] key and press

to store:

2 DIR : Enables flow measurement in 2 direc-

tions (fig. D.7).

TRAN. TIME: Output signal is proportional to the

measured transit time of the acoustic

signal.

**NOTE:** This function requires:

- PULSRATE setting, Fct. 3.4.2

- PULSRATE at full flow, Fct. 3.4.3

- Transit time at full flow, Fct. 3.1.2 (see example in description of Fct. 3.1.2)

NO SIGNAL: Output signal indicates "signal loss".

OFF : No frequency output.

F/R IND. F : Output signal as flow direction indica-

tion, 0% at + flow direction and 100% at - flow direction (Fig. D.8).

1 DIR : Flow measurement in 1 direction (+)

only (Fig. D.9).

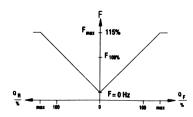


Fig. D.7 : Bi-directional flow(F)

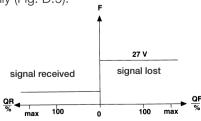


Fig. D.8: Flow direction indication(F)



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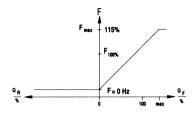


Fig.D.9: Positive flow (F)

3.4.2 PULSOUTP. : Frequency output mode

Select one of the two frequency output modes using the

♠ key and press to store:

PULSE/UNIT : Pulses per unit of volu-

me.

PULSRATE : Pulses per unit of time

at full scale flow.

Example of PULSE/UNIT

Pulse value : 10 pulses per m3 (set

via Fct.3.4.3)

After 60 m3 have passed : Output: 600 pulses

since start.

Example PULSRATE :

Full scale setting : 1000 liters per second

(set via Start Up Menu)

Pulse rate full scale flow : 1000 pulses per second

(set via Fct. 3.4.3)

At 600 liters per second : Output: 600 Hz signal.

3.4.3 PULS/UNIT - PULSRATE

(pulse/unit or pulse rate depends on selection in 3.4.2)

PULSE/UNIT : Program number of pul-

ses per unit of volume:

Pulse per volumetric unit: Range (maximum):

 PulS/m3
 9.9990 E 8

 PulS/Liter
 9.9990 E 5

 PulS/US G
 3.7850 E 6

PULSRATE : Program pulses per unit

of time at full scale flow:

Pulse rate unit: Range:

Min. Max.

 PulSe/Sec
 2.7778 E-3
 1.0000 E 4

 PulSe/min
 1.6667 E-1
 6.0000 E 5

 PulSe/hr
 1.0000 E 1
 3.6000 E 7

3.4.4 T - CONST. F: Time constant of fre-

quency output

(see 3.3.5 T- CONST.I)

Program one of the two options for the time constant of the frequency output:

T < F > = T < I > : Equal to the time con-

stant of the current out-

put (see 3.3.5).

T<F> = 40 msec



\_\_\_\_ UFM 600 T

GB/USA : English

← to store:

D

F

NI

3.5.2 OUTP.	HOLD	:	Hold outputs during programming	
available and all	output leve on active a	els will no Il outputs	ring mode no flow data rmally drop to zero. s maintain their last va ted.	
Caution should loop since the	be observe controller m responsible	ed, if the s ay have t	at the user's discreti signal is used in a con to be switched to "ma nel should be notified t	trol nu-
Select YES or I store.	NO using th	ne 🚹	key and press	to
3.5.3 UNIT	TEXT			
With this function programmed, e			user defined unit can	be
The format of the	ne unit is pre	eprogram	med:	
With both → can be program			ext (capital and numbe tore.	ers)

3.5.0 SPEC. FCT. : set special functions

3.5.1 LANGUAGE : Display language

Select a language option using the key and press

German

French

Dutch

#### 3.5.4 FACT. QUANT.

If a user defined unit is applied the quantity factor has to be programmed.

This must be the conversion ratio into m3.

In the example with Barrels/Day (see 3.5.3) the quantity unit Barrel has to be converted into m3 (1 Barrel = 1.5898 E-1 m3).

#### 3.5.5 FACT. TIME

If a user defined unit is applied the time factor has to be programmed.

This must be the conversion ratio into seconds.

In the example with Barrels/Day (see 3.5.3) the time unit Day has to be converted into seconds (1 Day = 8.6400 E 4 seconds).

#### 3.5.6 SET DATE

Program the correct date in this function.

The actual date is included in the header of each data block that is stored.

On entering this function the date can be programmed in (mm-dd-vv) notation.

Programming the actual date is similar to that of numbers.

#### 3.5.7 SET TIME

Program the correct time in this function.

The actual time is included in the header of each data block that is stored.

Programming is similar to numbers.



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#### 3.5.8 DEFAULT SET

If this function is used all parameters will be reprogrammed to default settings (see Appendix 5).

(NOTE: factory settings are not affected by this function)

### **NOTE:** The Date, Time and Location data will be lost, too!!

This function should only be used to restart programming if the cause of a PARAMERROR can not be found; it offers a start with no error messages as far as the parameters are concerned.

3.5.9 SOFTW. V. NR.

This function can be entered to view the number of the current software version.

No action can be taken here.

3.6.0 COMM. DATA : set RS 232 output / store

3.6.1 OUTP, PARAM.

With this function all programmed parameters can be sent to a PC via the RS 232 output.

**NOTE:** No error message is given if a communication error (no RS 232 response) occurs!

Select YES and press 

to start the output.

3.6.2 OUTP, DATA

With this function all collected data stored in the RAM can be sent to a PC via the RS 232 output.

**NOTE**: No error message is given if a communication error (no RS 232 response) occurs!

Select YES and press 🗗 to start the output.

3.6.3 SEL. COMM.

With this function the output medium can be selected to which the data is sent as programmed in 3.2.0 and 3.6.4.; the intervals are programmed in 3.6.4.

The options are:

OFF : No output at all (only on LCD).
BOTH : Data is stored in the RAM as well as

sent to the RS 232 output.

OUTPUT: Data is send to the RS 232 output

only.

STORE: Data is stored in the RAM only.

For settings of the PC terminal program see: C 4.3.



# **ALTOSONIC** Programming mode

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#### 3.6.4 INTERVAL (not visible if SEL. COMM is OFF)

Program the interval between successive data collections as programmed in 3.6.3.

Range: 01 - 60 min

3.6.5 LOCATION : Location

If this function is activated the location, as programmed in the Start Up Menu, is recorded in the header of each data block that is stored or sent to RS 232.

Select YES or NO using the 1 key and press 1 to store.

3.6.6 RESET DATA

If STORE is programmed in function 3.6.3 all data blocks are stored in the internal RAM.

With this function the RAM can be cleared, to be able to store new data (up to 390 blocks).

**NOTE:** the parameter settings are not affected by this function.

Select YES or NO using the key and press to store.



# **ALTOSONIC** Programming mode

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D.5 Sub Menu : 2.0.0 TEST

2.1.0 DISPLAY

2.1.1 DISPLAY TEST

All individual segments of the liquid crystal display are activated in a sequence ending in a flashing display of all segments.

No action can be taken.

Select YES and press to start the test.

2.2.0 PROCESSOR

The microprocessor performs a self test.

No action can be taken.

Select YES and press to start the test.

If the test does not end with the message NO ERROR contact your dealer.

Press (4) to exit the function.

2.3.0 CURR. OUTP. I

2.3.1 TEST

To check the functioning of both the analog output and the externally connected instruments and wiring, the analog output can be set to 7 specific values:

0, 4, 8, 12, 16, 20 and 22 mA

The value shown on the display should match the indication on the instrument connected to the current output.

Press to start the test and use the

key to select output current.

Press to exit the function.

2.4.0 FREQ. OUTPUT

#### 2.4.1 TEST

To check the functioning of both the frequency output and the externally connected instruments and wiring, the frequency output can be set to 5 specific values:

1, 10, 100, 1000 and 10000 Hz

The value shown on the display should match the indication on the instrument connected to the frequency output.

Press → to start the test and use the

↑ key to select output frequency.

Press to exit the function.



# **ALTOSONIC** Programming mode

UFM 600 T

#### D.6 Parameter errors

If discrepancies in the parameters entered are found the microprocessor will display the message "PARAMERROR" thus preventing you from storing parameters that are incorrect.

The PARAMERROR menu can appear at the end of both the Start Up menu and the Installation Menu.

A third main menu is available now: Fct. 4.0.0 PARAM.ERROR

In this menu only one submenu is available at a time; only the submenu that applies to the discrepancy to be corrected will be displayed.

List of possible submenus and functions within PARAMER-ROR:

4.0.0	PARAMERROR	Discrepancy:
4.1.0	V RANGE	The combination of the diameter, wall and lining thickness and the full scale flow rate is not feasible.
4.1.1 4.1.2 4.1.3 4.1.4	DIAMETER PIPEWALL LINING TH. FULL SCALE	
4.2.0	I RANGE	[I 100 PCT] does not exceed [I 0 PCT] by at least 4 mA
4.2.1 4.2.2	I 0 PCT I 100 PCT	[10101] by at least 4 IIIA
4.3.0	I MAX mA	[I MAX] is not equal to or greater than [I 100 PCT]
4.3.1 4.3.2	I 100 PCT I MAX	
4.4.0	CUTOFF	CUTOFF ON exceeds CUTOFF OFF

4.4.1 4.4.2 4.4.3	L.F. CUTOFF CUTOFF ON CUTOFF OFF	
4.5.0	F>10KHZ	Output frequency is too high, must be less than 10kHz
4.5.1 4.5.2 4.5.3 4.5.4	FULL SCALE PULSOUTP. PULSRATE PULS/UNIT	must be less than Toki iz
4.6.0	APPL.DATA	Programmed sonic velocities are not within the specified range
4.6.1 4.6.2 4.6.3	PIPE MAT. LIQUID LINING MAT.	within the specified range
4.7.0	FREQ.OUTPUT	The combination of F-Function and
4.7.1 4.7.2	FUNCTION F PULSOUTP.	Pulsoutput is not feasible

Activate the submenus and functions as described in section D.2.

After the correct parameter values have been entered the PARAMERROR menu can be exited by pressing the 4 key 7 times; the parameters are checked and saved and the program stops at the beginning of the Start Up menu.



#### NOTE:

Instead of activating the PARAMERROR menu the INSTALLATION or TEST menus can be entered by using the key.

# **ALTOSONIC** Maintenance

UFM 600 T

E.1 Mains Fuse

The mains fuse is located in the connection compartment.

**NOTE:** ONLY USE FUSES AS INDICATED NEXT TO THE FUSE

FITTING TO PREVENT SERIOUS DAMAGE TO THE

ELECTRONIC EQUIPMENT (see Spare Parts).

If the fuse is blown regularly, contact your dealer.



# ALTOSONIC Technical Data

#### UFM 600 T

#### F.1 General

Measuring beam 1

Diameter range 50 ... ≥ 3000 mm (2" ... ≥120")

Pipe wall thickness  $\leq 40 \text{ mm} (\leq 1.6)$ 

Pipe wall materials metal, plastics, ceramics,

asbestos-cement with or without firmly attached linings or coatings

Fluids any clean homogeneous liquid

with a gaseous or solid particle

content ≤1% by volume

Fluid temp. -25 to +120 °C (-13 to 248 °F)

Error limits 1 to 3%, depending on application

Reproducibility up to 0.2%

Time constant 0.04 to 3600 s

Outputs current, frequency/pulse and RS

232 for data transfer to PC

Display for indication of all measuring data,

calculated transducer distance, error messages and transit time

valuosatria flavu vata tatal flavu

Measured values volumetric flow rate, total flow,

transit time and flow direction (for-

ward/reverse)

Cable length:

Standard 5 m (15 ft)

Optional > 5 m...≤ 300 m(>15 ft...≤ 900 ft)

### F.2 Transducers & Clamp-on Set

Transducers single beam; 2x RS 600

Diameters A single clamp-on set suitable for

50 mm (2") to 2000 mm (80") pipes, incorporating 2 rails with

cm-scale and straps

Materials:

Transducer housing nickel plated brass with plastic

contact surface.

Rails aluminium, anodized

Protection category

nec-(standard):

IP 65 (transducers with BNC contors) acc. DIN 40050 / IEC 144

(option): IP 68 (cables fix connected to the

transducers)

Ambient temp. -25 to 60 °C

Process liquid temp. -25 to 120 °C

**NOTE:** High temperature sensor cable optional available.



## **ALTOSONIC** Technical Data

UFM 600 T

## F.3 Signal Converter

Version UFC 600 T

Outputs fully programmable

galvanically insulated

- analog 0 to 20 mA, or 4 to 20 mA, or

I[0%] to I[100%] programmable.

load ≤ 100 Ohm

- frequency/pulse

pulse rate 0.0028 Hz.(= 10 pulses/hour) to

10000 Hz. or pulses per liter, m3, US gallon, or per user defined unit

Low flow cut off programmable

in : 1 to 19% out: 2 to 20% **Local display:** back-lit LCD

Display functions actual flow rate, forward-, reverse-

and sum-totalizers (7 digit), transition time and error messages; each programmable for continu-

ous or sequential display

Display units

actual flow liters, m3, or US gallons per sec-

ond, minute or hour and one free

programmable unit

totalizers liters, m3, or US gallons and one

freely

programmable unit; min. one year

overflow time

Display language English, French, German, Dutch;

other languages on request

Display arrangement 8 digit, 7 element numerical and

sign display,

1st line symbols for push-button acknow-

ledgement

2nd line 10 character 14 segment text dis-

play.

3rd line 4 markers to identify the actual

display function

functions location, actual flow rate (and

direction), totalizer, time, transit-

time and error messages



# ALTOSONIC Technical Data

\_\_\_\_ UFM 600 T

## **Power supply**

AC power supply: 85 - 264 VAC DC power supply: 18 - 32 VDC

Power consumption  $\leq$  10 VA AC

≤ 8 W DC

**Housing** Cast aluminium

**Ambient temp.** -25 to +50 °C (-13 to 122°F)

Protection category

IP 65, acc. to IEC 529 (equivalent to NEMA 4x)

Full scale value (Din= inner pipe diameter)

<u>lower limit</u>  $(V_{100\% \text{ min}} = 0.5 \text{ m/s})$ 

 $Q_{100\%min} [m^3/h] = ( Din [mm]/100 )^2 * 14.2$ 

 $Q_{100\%min} [m^3/h] = ( Din [inch] )^2 * 0.9$  $Q_{100\%min} [USGPM] = ( Din [inch] )^2 * 3.9$ 

<u>upper limit</u>  $(V_{100\%max} = 17.1 \text{ m/s})$ 

 $Q_{100\%max}$  [m3/h] = (Din [mm])  $^2 * 0.05$  $Q_{100\%max}$  [m3/h] = (Din [inch])  $^2 * 31.25$ 

 $Q_{100\%max}[USGPM] = (Din [inch])^2 * 138$ 

Reynolds

**number** Re > 10.000

Repeatability

 $R = \frac{0.2}{V_{m} * D_{i}}$  [%]

R = repeatability in %
V<sub>m</sub> = flow velocity [m/s]
D<sub>i</sub> = inner pipe diameter [m]



# **ALTOSONIC** Appendix

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## **APPENDIX 1: Pipe Material Sonic Velocities**

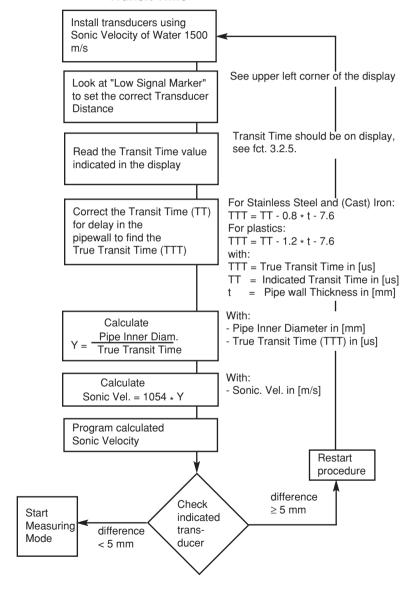
MATERIAL NAME	SONIC VELOCITY
Carbon Steel c≤0.3%	3064 m/s
Carbon Steel c > 0.3%	3173 m/s
Carbon-Moly Steel	3173 m/s
Cr-Mo-Steel Cr ≤ 3%	3173 m/s
Cr-Mo-Steel 5% ≤ Cr ≤ 9%	3040 m/s
Chromium Steel (stainless)	3177 m/s
Austenitic St. Steel (general)	3120 m/s
St. Steel 304	3120 m/s
St. Steel 310	3120 m/s
St. Steel 316	3120 m/s
St. Steel 321	3120 m/s
St. Steel 347	3120 m/s
Grey Cast Iron	2125 m/s
Monel 67 Ni- 30 Cu	2810 m/s
Monel 66 Ni- 29 Cu- Al	2823 m/s
Alloy 706 (90 Cu - 10 Ni)	2334 m/s
Alloy 710 (80 Cu - 20 Ni)	2582 m/s
Alloy 715 (70 Cu - 30 Ni)	2513 m/s
Copper Alloys 120 and 122	2149 m/s
Lead-Tin-Bronze alloy 922 A9	1985 m/s
Commercial Brass (65 Cu-35 Zn)	2060 m/s
Aluminium	3269 m/s
Incoloy 800/800H Ni-Fe-Cr	3024 m/s
Inconel 600 Ni-Cr-Fe	3004 m/s
Commercial pure Titanium	2975 m/s
PP	2120 m/s
PVC	2120 m/s
Perspex	2730 m/s
Asbestos Cement	4195 m/s

**APPENDIX 2 : Sonic Velocities of Liquids** 

LIQUID NAME	SONIC VELOCITY at 20°C
Acetone	1174 m/s
Benzene	1295 m/s
Carbon Disulphide	1149 m/s
Caster Oil	1477 m/s
Chloroform	987 m/s
Diesel Oil	1250 m/s
Ethanol	1207 m/s
Ethanol Amide	1724 m/s
Ethyl Ether	985 m/s
Ethylene Glycol	1658 m/s
Freon	690 m/s
Glycerol	1904 m/s
Kerosine	1324 m/s
Mercury	1407 m/s
Methanol	1103 m/s
Methylene lodide	980 m/s
Nitrobenzene	1460 m/s
Turpentine	1326 m/s
Water ( 0 - 20°C )	1484 m/s
Water (21- 40°C)	1505 m/s
Water ( 41 - 60°C )	1529 m/s
Water ( 61 - 80°C )	1538 m/s
Sea Water	1531 m/s
Xylene Hexafluoride	879 m/s

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### APPENDIX 3 : Sonic velocity calculation Using Indicated Transit Time



#### **APPENDIX 4: Exponential Notation**

Most values have to be entered in the exponential notation as will be made clear by the message displayed.

Exponential Notation: Y.YYYY E±Z

This indicates that Y.YYYY should have a value between 1.0000 and 9.9999 (1.0000 < Y.YYYY < 9.9999).

The value of Z gives the multiplication factor, e.g.:

Z = +0 indicates Y.YYYY x 1

Z = +1 indicates Y.YYYY x 10

Z = +2 indicates Y.YYYY x 100

Z = +3 indicates Y.YYYY x 1000

etc.

For small values the exponent Z will be negative. (Press ARROW UP when E is blinking)

Z gives the dividing factor, e.g.:

Z = -1 indicates Y.YYYY / 10

Z = -2 indicates Y.YYYY / 100 Z = -3 indicates Y.YYYY / 1000

etc.

#### Examples:

program: 1.0345 as 1.0345 E+0 16.167 as 1.6167 E+1 550.12 as 5.5012 E+2 2987.1 as 2.9871 E+3

### and with negative exponents:

0.335 as 3.3500 E-1 0.0205 as 2.0500 E-2 0.0015 as 1.5000 E-3



## **APPENDIX 5 : Default Settings + Example of Output Parameters**

The next page shows all parameters after the function Default Set (3.5.8) has been used. These are the default settings as programmed by the factory.

The way the settings are presented is identical to the RS 232 output after using function Output Parameters (3.6.1).

1.0.0.	STARTUP DIAMETER	1.0000E+2	3.3.0. 3.3.1	CURR. OUTF FUNCTION I	PUT 1 DIR.
		mm	3.3.2	I 0 PCT.	
	PIPE WALL	1.0000E+0			04 mA
	PIPE MAT.	mm	3.3.3	I 100 PCT.	20
	LINING	3.1700E+3	3.3.4	I MAX mA	mA
	LIQUID	NO			22 mA
	FULL SCALE	1.5000E+3 WATER	3.3.5	T-CONST.	4.0000E+0 Sec
		1.0000E+2 m <sup>3</sup> /hr	3.4.0 3.4.1	FREQ.OUTPU FUNCTION F	JT
	LOCATION		3.4.2	PULSOUTP.	1 DIR.
	SENS. DIST.	4.4329E+1	3.4.3	PULS/UNIT	PULS/UNIT
	ZERO SET.	mm			1.0000E+0 Puls/m <sup>3</sup>
			3.4.4	T-CONST.	40 mSec
3.0.0. 3.1.0 3.1.1	INSTALL. FLOW DATA PRIM. CORR.		3.5.0 3.5.1	SPEC. FCT. LANGUAGE	GB/USA
3.1.2	TRAN, RANG	1.0000E+0	3.5.2	OUTP. HOLD	
0.1.2	INAN. NANG	3.0000E+2	3.5.3	UNIT TEXT	/_
3.1.3	L.F. CUTOFF	uSec	3.5.4	FACT. QUAN	T. ,
3.1.4	CUTOFF ON	YES 01%	3.5.5	FACT. TIME	1.0000E+0
3.1.5	CUTOFF OFF	02%	3.5.6	SET DATE	1.0000E+0
3.2.0 3.2.1	DISPLAY DISP. FLOW	m <sup>3</sup> /hr	3.5.7	SET TIME	01-01-90
3.2.2	DISP. TOTAL		3.6.3	SEL. COMM.	
3.2.3	UNIT TOTAL	+ 101 m <sup>3</sup>	3.6.6	RESET DATA	
3.2.4	ERROR MSG				
3.2.5	NO MESSA DISP.TRAN.T				
3.2.6	CYCL. DISP.	NO			
		NO			89

# ALTOSONIC Appendix

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## **APPENDIX 6: Spare Parts**

Krohne ordering number	Description	Number per UFM 600 T	Type/remarks
230262- 01 231266- 01	Mounting Rail Cable, coax	2 1	UL 600R (with slots) 5 m, BNC-connectors
(coded) 231266- 02 231266- 03 (coded)	Cable, coax Cable, coax	1 (1)	5 m, BNC-connectors 10 m, BNC-connectors
231266- 04 230271- 02 230306- 02 53089001 53063201 53063203 231021- 06 50567800	Cable, coax Transducer Sonic coupling great Tape measure Small Mounting stratege Mounting stratege Disc Fuse	1 ap 2	10 m, BNC-connectors UL 600 R Tube, Blasolube, 70 g 500 cm (192") 60-215 60-540 UFM 600/ 3 1/2" Disc T zoom A, 20 x 5 mm 85V -264 VAC
50782300 7.3071831 53133301 S 153000364	Fuse, main Manual Cable RS232 Ultrasonic wall thick gauge	1 1 1 Kness (1)	T 1.6 mA, 20 x 5 mm UFM 600 T T-Mike, incl. probes, AC/DC converter, couplant gel

NOTE: Numbers between brackets (..) are not part of standard delivery.